IN THE CLAIMS:

This listing of claims will replace all prior versions and listings of claims in the application. Where claims have been amended and/or canceled, such amendments and/or cancellations are done without prejudice and/or waiver and/or disclaimer, and Assignee reserves the right to claim this subject matter in a continuing application:

1. (Previously Presented) A method comprising:

    scanning an original comprising one or more objects;

    generating a preview window of the scanned original, wherein the preview window includes a profile of at least one of said one or more objects, and wherein said profile defines a confined area of the preview window;

    receiving a selection of at least one profile included in said preview window;

    determining a scan area based at least in part on said selection; and

    scanning said scan area.

2. (Previously Presented) The method according to claim 1, wherein said preview window comprises a display of said one or more objects.

3. (Currently Amended) The method according to claim 2, wherein [[the]] said profile of said object corresponds with the location of the object in said original.

4. (Previously Presented) The method according to claim 3, wherein said profile and said location of said object are determined based at least in part on information obtained from said scanning.

5. (Previously Presented) The method according to claim 4, wherein said information comprises gray scale data.

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6. (Previously Presented) The method according to claim 4, wherein said information comprises pixel data, and said profile and said location of said object is determined based at least in part on said pixel data.

7. (Previously Presented) The method according to claim 4, wherein said information comprises object edge data.

8. (Currently Amended) The method according to claim [[4]] 1, wherein said selection is performed by a user.

9. (Currently Amended) The method according to claim 1, wherein said selection is performed automatically based at least in part on one or more parameters of the at least one or more profiles profile.

10. (Currently Amended) The method according to claim [[1]] 9, wherein said parameters comprise one or more of: size of the one or more profiles, shape of the one or more profiles, number of the one or more profiles, and location of the at least one or more profiles profile.

11. (Previously Presented) The method according to claim 1, further comprising generating a profile of all the objects in the original.

12. (Previously Presented) The method according to claim 1, further comprising generating a single profile for a plurality of objects in the original.

13. (Previously Presented) A method comprising:

        scanning an original comprising one or more objects;

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generating a preview window of the scanned original, wherein the preview window includes a

profile of at least one of said one or more objects, and wherein said profile defines a confined area of

the preview window and corresponds to the location of a respective object of said original;

defining a scan area to include at least a portion of said one or more objects; and

scanning said scan area.

14. (Previously Presented) The method according to claim 13, wherein said profile and said location of

said object are determined based at least in part on information obtained from said scanning.

15. (Previously Presented) The method according to claim 14, wherein said information comprises gray

scale data.

16. (Previously Presented) The method according to claim 13, wherein said information-comprises

pixel data, and said profile and said location of said object is determined based at least in part on said

pixel data.

17. (Previously Presented) The method according to claim 13, wherein said information comprises

object edge data.

18. (Previously Presented) The method according to claim 13, further comprising generating a single

profile for a plurality of objects in the original.

19. (Previously Presented) The method according to claim 13, further comprising generating a profile

of all the objects in the original.

20. (Previously Presented) A scanner comprising:

a scanning flatbed for supporting an original, said original including one or more objects;

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a scanning module for scanning said original to generate information;

a logic module for determining a location of an object in the original and generating a preview of the original including a profile of the object based at least in part on said information;

a display module for displaying the preview including a profile of said object; and

an evaluating module for receiving a selection of at least a portion of said preview window.

21. (Previously Presented) The scanner of claim 20, wherein said scanning module is further adapted to scan the portion of said object corresponding with said selection.

22. (Previously Presented) The scanner of claim 20, wherein said selection is performed by a user.

23. (Previously Presented) The scanner of claim 20, wherein the profile of said object corresponds with the location of the object within said original.

24. (Previously Presented) The scanner of claim 20, wherein said profile and said location of said object are determined based at least in part on information obtained from said scanning.

25. (Previously Presented) The scanner of claim 20, wherein said information comprises gray scale data.

26. (Previously Presented) The scanner of claim 20, wherein said information comprises pixel data, and said profile and said location of said object is determined based at least in part on said pixel data.

27. (Previously Presented) The scanner of claim 20, wherein said information comprises object edge data.

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